SUM-1K0SxxxMx

Rev.C

1000W Programmable Driver with INV Digital Dimming

Features

- Hot-plugging Protection
- Parallel LED Protection
- Ultra High Efficiency (Up to 96%)
- Full Power at Wide Output Current Range (Constant Power)
- Adjustable Output Current (AOC) with Programmability
- Isolated 0-10V/PWM/Resistor/3-Timer-Modes Dimmable
- Adjustable Dimming Curve
- INV Digital Dimming, UART Based Communication Protocol
- Dim-to-Off with Standby Power ≤ 0.5W
- Minimum Dimming Level with 5% or 10% Selectable
- Hold Time Adjustable
- Fade Time Adjustable
- Always-on Auxiliary Power: 12Vdc, 250mA
- Low Inrush Current
- Output Lumen Compensation
- End-of-Life Indicator
- Input Surge Protection: DM 6kV, CM 10kV
- All-Around Protection: IOVP, IUVP, OVP, SCP, OTP
- IP66/IP67 and UL Dry/Damp/Wet Location
- TYPE HL, for Use in a Class I, Division 2 Hazardous (Classified) Location
- 5 Years Warranty





Description

The *SUM-1K0SxxxMx* series is a 1000W, constant-current, programmable and IP66/IP67 rated LED driver that operates from 90-305Vac input with excellent power factor. Created for many lighting applications including high mast, sports, UV-LED, aquaculture and horticulture, etc. It provides an auxiliary voltage and dim-to-off functionality for powering low voltage, wireless controls. The dimming control supports 0-10V dimming as well as two-way communication via Digital Dimming, a UART based communication protocol. The high efficiency of these drivers and compact metal case enables them to run cooler, significantly improving reliability and extending product life. To ensure trouble-free operation, protection is provided against input surge, input under voltage, input over voltage, output over voltage, short circuit, and over temperature.

Models

| Adjustable Output | Full-Power Current | Default Output | Output Voltage | Max. Output Efficiency | | | ical Factor | Model Number |
|----------------------|-----------------------------|-------------------|-------------------|------------------------|-------|--------|----------------|------------------------------|
| Current Range (A) | Range (A) ⁽¹⁾ | Current (A) | Range (Vdc) | Power (W) | (2) | 120Vac | 220Vac | (3) (4) |
| 0.32-4 | 3.2-4 | 3.3 | 175-312 | 1000 | 95.0% | 0.99 | 0.96 | SUM-1K0S400Mx |
| 0.672-8.4 | 6.72-8.4 | 7.7 | 84-149 | 1000 | 95.0% | 0.99 | 0.96 | SUM-1K0S840Mx |
| 1.85-21 | 18.5-21 | 18.5 | 34-54 | 1000 | 95.5% | 0.99 | 0.96 | SUM-1K0S21AMx ⁽⁵⁾ |

Notes: (1) Output current range with constant power at 1000W.

(2) Measured at 100% load and 220Vac input (see below "General Specifications" for details).

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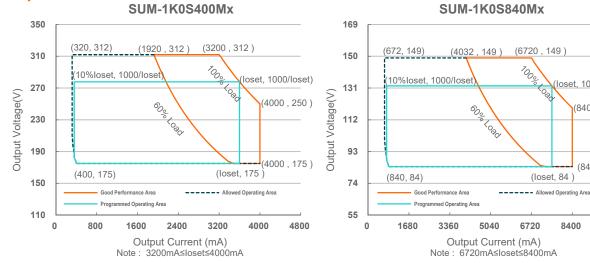
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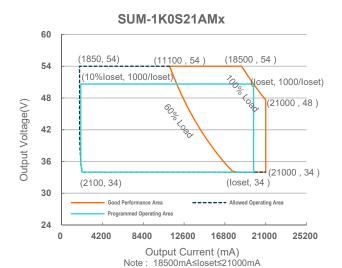
10080

8400

- (3) Certified input voltage range: UL, FCC 100-277Vac; otherwise: 100-240Vac
- (4) x = G are UL Recognized, CE, etc. models, x = T are UL Recognized, CE (built-in-use), etc. models.
- (5) SELV output

I-V Operation Area





Input Specifications

| Parameter | Min. | Тур. | Max. | Notes |
|------------------|---------|------|----------|---------------------------|
| Input AC Voltage | 90 Vac | - | 305 Vac | |
| Input DC Voltage | 127 Vdc | - | 300 Vdc | |
| Input Frequency | 47 Hz | - | 63 Hz | |
| Lookogo Current | - | - | 0.75 MIU | UL 8750; 277Vac/ 60Hz |
| Leakage Current | - | - | 0.70 mA | IEC 60598-1; 240Vac/ 60Hz |

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Input Specifications (Continued)

| Parameter | Min. | Тур. | Max. | Notes |
|----------------------------------|------|------|-----------------------|--|
| Innuit AC Current | - | - | 10.07 A | Measured at 80% load and 120 Vac input. |
| Input AC Current | - | - | 5.39 A | Measured at 100% load and 220 Vac input. |
| Inrush Current(I ² t) | - | - | 2.89 A ² s | At 220Vac input, 25°C cold start, duration=17.6 ms, 10%lpk-10%lpk. |
| PF | 0.90 | - | - | At 100-277Vac, 50-60Hz, 60%-100% Load |
| THD | - | - | 20% | (600 - 1000W) |
| THD | - | - | 10% | At 220-240Vac, 50-60Hz, 75%-100% Load (750 - 1000W) |

Output Specifications

| Parameter | Min. | Тур. | Max. | Notes |
|--|--------------------------------|-------------|--------------------------------|---|
| Output Current Tolerance | -5%loset | - | 5%loset | 100% load |
| Output Current Setting(loset Range) | | | | |
| SUM-1K0S400Mx SUM-1K0S840Mx SUM-1K0S21AMx | 320 mA 672 mA 1850 mA | - - - | 4000 mA 8400 mA 21000 mA | |
| Output Current Setting Range with Constant Power SUM-1K0S400Mx SUM-1K0S840Mx SUM-1K0S21AMx | 3200 mA 6720 mA 18500 mA | - - - | 4000 mA 8400 mA 21000 mA | |
| Total Output Current Ripple (pk-pk) | - | 5%lomax | 10%lomax | 100% load, 20 MHz BW |
| Output Current Ripple at < 200 Hz (pk-pk) | - | - | 2%lomax | 70%-100% load |
| Startup Overshoot Current | - | - | 10%lomax | 100% load |
| No Load Output Voltage SUM-1K0S400Mx SUM-1K0S840Mx SUM-1K0S21AMx | - - - | - - - | 350 V 170 V 60 V | |
| Line Regulation | - | - | ±0.5% | 100% load |
| Load Regulation | - | - | ±3.0% | |
| Turn-on Delay Time | - | - | 0.5 s | Measured at 120-277Vac input, 60%-10 0% Load |
| Temperature Coefficient of loset | - | 0.03%/°C | - | Case temperature = 0°C ~Tc max |
| 12V Auxiliary Output Voltage | 10.8 V | 12 V | 13.2 V | |
| 12V Auxiliary Output Source Current | 0 mA | - | 250 mA | Return terminal is "Dim-" |
| 12V Auxiliary Output Transient Peak Current@6W | - | - | 500 mA | 500mA peak for a maximum duration of 2.2ms in a 6.0ms period during which time the average should not exceed 250mA. |
| 12V Auxiliary Output Transient Peak Current@10W | - | - | 850 mA | 850mA peak for a maximum duration of 1.3ms in a 5.2ms period during which time the average should not exceed 250mA. |

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1000W Programmable Driver with INV Digital Dimming

General Specifications

| Parameter | Min. | Тур. | Max. | Notes |
|---|---------------------|------------------|----------|--|
| Efficiency at 120 Vac input: | | · · | | |
| SUM-1K0S400Mx | | | | |
| lo= 3200 mA lo= 4000 mA | 90.0% 89.0% | 92.0% 91.0% | - | Measured at 80% load and steady-state |
| SUM-1K0S840Mx | 09.070 | 91.0% | - | temperature in 25°C ambient; |
| lo= 6720 mA | 91.0% | 93.0% | - | (Efficiency will be about 2.0% lower if |
| Io= 8400 mA SUM-1K0S21AMx | 90.0% | 92.0% | - | measured immediately after startup.) |
| Io= 18500 mA | 91.0% | 93.0% | - | |
| lo= 21000 mA | 91.0% | 93.0% | - | |
| Efficiency at 220 Vac input: SUM-1K0S400Mx | | | | |
| lo= 3200 mA | 93.0% | 95.0% | - | |
| Io= 4000 mA SUM-1K0S840Mx | 93.0% | 95.0% | - | Measured at 100% load and steady-state temperature in 25°C ambient; |
| Io= 6720 mA | 93.0% | 95.0% | _ | (Efficiency will be about 2.0% lower if |
| Io= 8400 mA | 93.0% | 95.0% | - | measured immediately after startup.) |
| SUM-1K0S21AMx lo= 18500 mA | 93.5% | 95.5% | | |
| lo= 21000 mA | 93.5% | 95.5% | - | |
| Efficiency at 277 Vac input: | | | | |
| SUM-1K0S400Mx lo= 3200 mA | 93.5% | 95.5% | _ | |
| lo= 4000 mA | 93.5% | 95.5% | - | Measured at 100% load and steady-state |
| SUM-1K0S840Mx | 00.00/ | 05.00/ | | temperature in 25°C ambient; |
| lo= 6720 mA lo= 8400 mA | 93.0% 93.0% | 95.0% 95.0% | - | (Efficiency will be about 2.0% lower if measured immediately after startup.) |
| SUM-1K0S21AMx | | | | modeling initionality and startup.) |
| Io= 18500 mA Io= 21000 mA | 94.0% 94.0% | 96.0% 96.0% | - | |
| | 94.070 | | - | |
| Standby Power | - | - | 0.5 W | Measured at 230Vac/50Hz; Dimming off |
| | | 206,000 | | Measured at 220Vac input, 80%Load and |
| MTBF | - | Hours | - | 25°C ambient temperature (MIL-HDBK- 217F) |
| | | 440.000 | | Measured at 220Vac input, 80%Load and |
| | - | 110,000 Hours | - | 70°C case temperature; See lifetime vs. Tc |
| Lifetime | | | | curve for the details |
| | - | 50,000 Hours | - | Measured at 220Vac input, 100%Load and 40°C ambient temperature |
| Operating Case Temperature for Safety Tc_s | -40°C | - | +90°C | 1 |
| Operating Case Temperature for Warranty Tc_w | -40°C | - | +80°C | Case temperature for 5 years warranty Humidity: 10%RH to 95%RH |
| Storage Temperature | -40°C | - | +85°C | Humidity: 5%RH to 95%RH |
| Dimensions | | I | <u> </u> | With mounting ear |
| Inches (L × W × H) | 15.31 × 3.54 × 1.91 | | | 16.30 × 3.54 × 1.91 |
| Millimeters (L × W × H) | • | 389 × 90 × 48.5 | <i>)</i> | 414 × 90 × 48.5 |
| Net Weight | - | 3500 g | - | |

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Dimming Specifications

| Parameter | | Min. | Тур. | Max. | Notes |
|----------------------------------|---|-----------------------------|--------|--------|---|
| | Absolute Maximum Voltage on the Vdim (+) Pin | | - | 20 V | |
| Source Curr | ent on Vdim (+) Pin | 90 uA | 100 uA | 110 uA | Vdim(+) = 0 V |
| Dimming Output Range with | SUM-1K0S400Mx SUM-1K0S840Mx SUM-1K0S21AMx | 10%loset | - | loset | 3200 mA ≤ loset ≤ 4000 mA 6720 mA ≤ loset ≤ 8400 mA 18500 mA ≤ loset ≤ 21000 mA |
| 10%-100% (Default) | SUM-1K0S400Mx SUM-1K0S840Mx SUM-1K0S21AMx | 320 mA 672 mA 1850 mA | - | loset | 320 mA ≤ loset ≤ 3200 mA 672 mA ≤ loset ≤ 6720 mA 1850 mA ≤ loset < 18500 mA |
| Dimming Output Range with | SUM-1K0S400Mx SUM-1K0S840Mx SUM-1K0S21AMx | 5%loset | - | loset | 3200 mA ≤ loset ≤ 4000 mA 6720 mA ≤ loset ≤ 8400 mA 18500 mA ≤ loset ≤ 21000 mA |
| 5%-100% (Settable) | SUM-1K0S400Mx SUM-1K0S840Mx SUM-1K0S21AMx | 160 mA 336 mA 925 mA | - | loset | 320 mA ≤ loset ≤ 3200 mA 672 mA ≤ loset ≤ 6720 mA 1850 mA ≤ loset < 18500 mA |
| Recommend Range | ded Dimming Input | 0 V | - | 10 V | |
| Dim off Volta | Dim off Voltage | | 0.5 V | 0.65 V | Default 0.40V dimension mode |
| Dim on Volta | Dim on Voltage | | 0.7 V | 0.85 V | Default 0-10V dimming mode. |
| Hysteresis | | - | 0.2 V | - | |
| PWM_in Hig | ıh Level | 3 V | - | 10 V | |
| PWM_in Lov | w Level | -0.3 V | - | 0.6 V | |
| PWM_in Fre | equency Range | 200 Hz | - | 3 KHz | |
| PWM_in Du | ty Cycle | 1% | - | 99% | |
| PWM Dimm Logic) | PWM Dimming off (Positive | | 5% | 8% | Dimming mode set to PWM in Inventronics Programing Software. |
| | PWM Dimming on (Positive | | 7% | 10% | |
| PWM Dimming off (Negative Logic) | | 92% | 95% | 97% | 1 |
| | ing on (Negative | 90% | 93% | 95% | 1 |
| Hysteresis | | - | 2% | - | |

Safety & EMC Compliance

| Safety Category | Standard |
|-----------------|-----------------------------------|
| UL/CUL | UL 8750, CAN/CSA-C22.2 No. 250.13 |
| CE | EN 61347-1, EN 61347-2-13 |
| СВ | IEC 61347-1, IEC 61347-2-13 |

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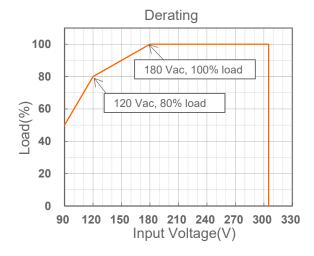
All specifications are typical at 25 $^{\circ}\mathrm{C}$ unless otherwise stated.

Safety & EMC Compliance (Continued)

| EMI Standards | Notes |
|--|---|
| EN IEC 55015 (1) | Conducted emission Test &Radiated emission Test |
| EN IEC 61000-3-2 | Harmonic current emissions |
| EN 61000-3-3 | Voltage fluctuations & flicker |
| FCC Part 15 ⁽¹⁾ | ANSI C63.4 Class B This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: [1] this device may not cause harmful interference, and [2] this device must accept any interference received, including interference that may cause undesired Operation. |
| EMS Standards | Notes |
| EN 61000-4-2 | Electrostatic Discharge (ESD): 8 kV air discharge, 4 kV contact discharge |
| | |
| EN 61000-4-3 | Radio-Frequency Electromagnetic Field Susceptibility Test-RS |
| EN 61000-4-3 EN 61000-4-4 | Radio-Frequency Electromagnetic Field Susceptibility Test-RS Electrical Fast Transient / Burst-EFT |
| | |
| EN 61000-4-4 | Electrical Fast Transient / Burst-EFT |
| EN 61000-4-4 EN 61000-4-5 | Electrical Fast Transient / Burst-EFT Surge Immunity Test: AC Power Line: Differential Mode 6 kV, Common Mode 10 kV |
| EN 61000-4-4 EN 61000-4-5 EN 61000-4-6 | Electrical Fast Transient / Burst-EFT Surge Immunity Test: AC Power Line: Differential Mode 6 kV, Common Mode 10 kV Conducted Radio Frequency Disturbances Test-CS |

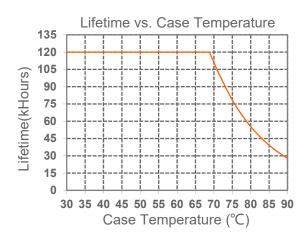
Note: (1) This LED driver meets the EMI specifications above, but EMI performance of a luminaire that contains it depends also on the other devices connected to the driver and on the fixture itself.

Derating

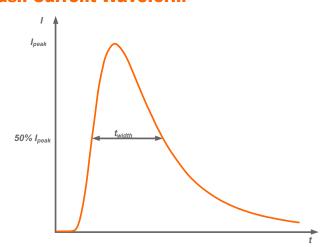


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Lifetime vs. Case Temperature

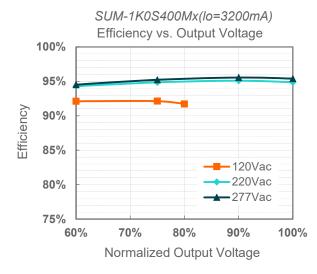


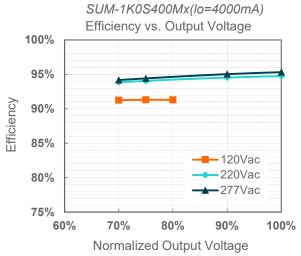
Inrush Current Waveform



| Input AC Voltage | I _{peak} | t _{width} (@ 50% Ipeak) | |
|------------------|-------------------|-------------------------------------|--|
| 220Vac | 14.8A | 4.12ms | |

Efficiency vs. Load





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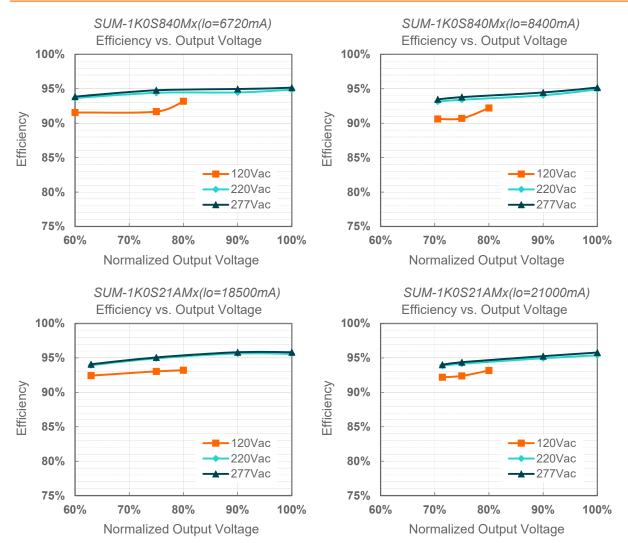
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Fax: 86-571-86601139

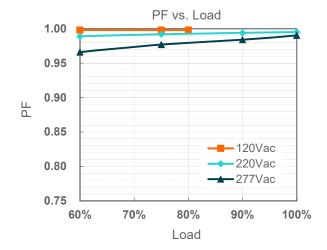
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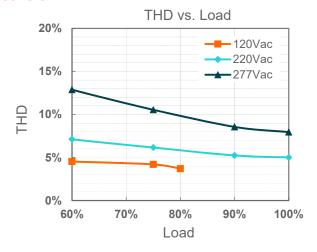


Power Factor



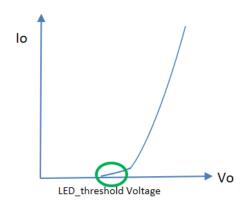
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Total Harmonic Distortion



Hot-plugging Protection

This feature protects LEDs when connecting to a driver that is already powered on. This is disabled by default and can be enabled through the Inventronics Programing Software.



LED threshold voltage (Vth) is the minimum voltage required for current to flow through the LED load. After this threshold is met, the LED forward voltage (Vf) increases as the current increases.

Set Vth close to, but higher than the actual LED threshold voltage for optimized performance. The greater the difference between the Vth setting and the actual LED threshold voltage, the higher the overshoot current will be. The Vth setting must be lower than Vf.

Please test, program, and tune this feature for each LED load design.

| Parameter | | Min. | Тур. | Max. | Notes | | |
|-----------|-------------------|---------------|-------|------|-------|--|--|
| | LED | SUM-1K0S400Mx | 175 V | - | 312 V | | |
| Hot- | Threshold | SUM-1K0S840Mx | 84 V | - | 149 V | Set Vth close to, but higher than the actual LED threshold voltage | |
| | | SUM-1K0S21AMx | 44 V | - | 54 V | vollage | |
| | Setting Tolerance | | -2% | - | 2% | | |

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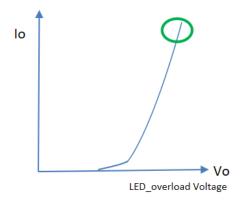
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Parallel LED Protection

This feature helps protect parallel LEDs from a high, overcurrent condition by limiting the voltage. This is disabled by default and can be enabled through the Inventronics Programing Software.



Set V_overload close to, but higher than the maximum forward voltage for optimized performance. The greater the difference between the V_overload setting and the maximum forward voltage, the higher the overload stress will be. The V_overload setting must be higher than Vf.

Please test, program, and tune this feature for each LED load design.

| | Parameter | | Min. | Тур. | Max. | Notes | |
|--------------|--------------------------------------|---------------|-------|------|-------|--|--|
| | | SUM-1K0S400Mx | 175 V | - | 325 V | | |
| Parallel Vol | Overload Voltage Setting Range | SUM-1K0S840Mx | 90 V | - | 155 V | Set V_overload close to, but higher than the maximum LEI forward voltage | |
| | | SUM-1K0S21AMx | 47 V | - | 56 V | iomara voltage | |
| | Setting Tolerance | | -2% | - | 2% | | |

Protection Functions

| Parameter | | Min. | Тур. | Max. | Notes | | |
|---------------------------------|--------------------------------------|--|--|----------------|---|--|--|
| Over Voltage P | rotection | Limits output voltage at no load and in case the normal voltage limit fails. | | | | | |
| Short Circuit Pr | rotection | | Auto Recovery. No damage will occur when any output is short circuited. The output shall return to normal when the fault condition is removed. | | | | |
| Over Temperat | ture Protection | Decreases of | output current, | returning to n | ormal after over temperature is removed. | | |
| Input Under Voltage | Input Under Voltage Protection | 70 Vac | 80 Vac | 90 Vac | Turn off the output when the input voltage falls below protection voltage. | | |
| Protection (IUVP) | Input Under Voltage Recovery | 75 Vac | 85 Vac | 95 Vac | Auto Recovery. The driver will restart when the input voltage exceeds recovery voltage. | | |
| Input Over | Input Over Voltage Protection | 310 Vac | 320 Vac | 330 Vac | Turn off the output when the input voltage exceeds protection voltage. | | |
| Voltage Protection (IOVP) | Input Over Voltage Recovery | 300 Vac | 310 Vac | 320 Vac | Auto Recovery. The driver will restart when the input voltage falls below recovery voltage. | | |
| | Max. of Input Over Voltage | - | - | 350 Vac | The driver can survive for 8 hours with a stable input voltage stress of 350Vac. | | |

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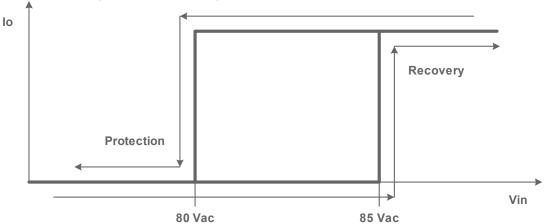
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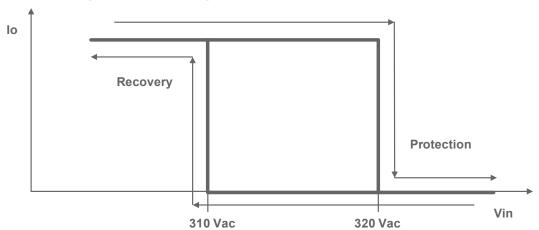
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Input Under Voltage Protection Diagram



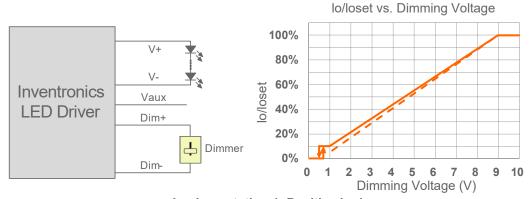
Input Over Voltage Protection Diagram



Dimming

0-10V Dimming

The recommended implementation of the dimming control is provided below.



Implementation 1: Positive logic

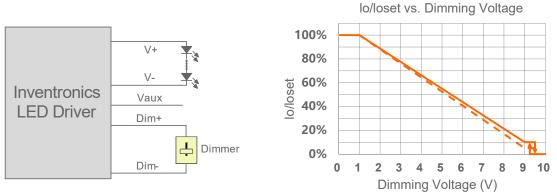
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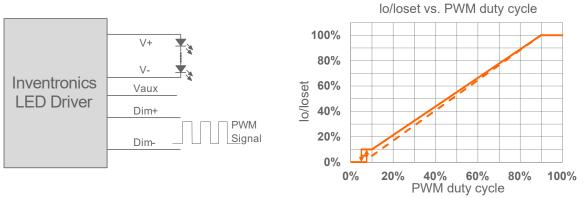
Implementation 2: Negative logic

Notes:

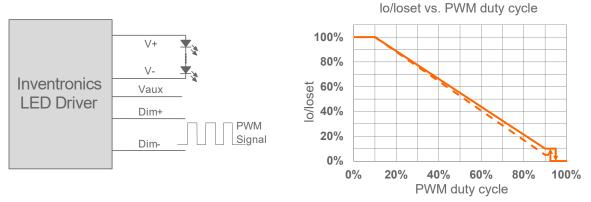
- 1. Do NOT connect Dim- to the output V- or V+, otherwise the driver will not work properly.
- 2. The dimmer can also be replaced by an active 0-10V voltage source signal or passive components like zener.
- 3. When 0-10V negative logic dimming mode and Dim+ is open, the driver will dim to off and be standby.

PWM Dimming

The recommended implementation of the dimming control is provided below.



Implementation 3: Positive logic



Implementation 4: Negative logic

Note:

- 1. Do NOT connect Dim- to the output V- or V+, otherwise the driver will not work properly.
- 2. When PWM negative logic dimming mode and Dim+ is open, the driver will dim to off and be standby.

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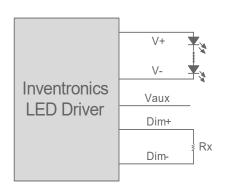
All specifications are typical at 25 °C unless otherwise stated.

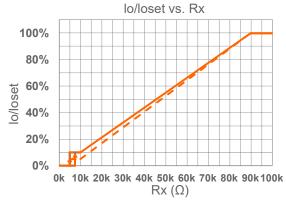
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1000W Programmable Driver with INV Digital Dimming

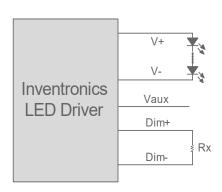
Resistor Dimming

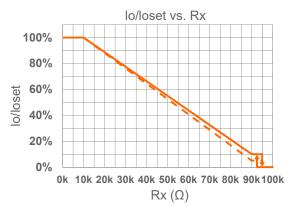
The recommended implementation of the dimming control is provided below.





Implementation 5: Positive logic





Implementation 6: Negative logic

Notes:

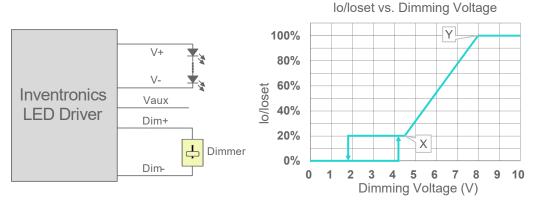
1. Do NOT connect Dim- to the output V- or V+, otherwise the driver will not work properly.

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2. When resistor negative logic dimming mode and Dim+ is open, the driver will dim to off and be standby.

Adjustable Dimming Curve

0-10V dimming curve can be set as corresponding dimming voltage by Inventronics Multi Programmer. Take the positive logic dimming as an example, the recommended implementation of the dimming control is provided below.



Implementation 7: Positive logic

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1000W Programmable Driver with INV Digital Dimming

Notes:

- 1. Do NOT connect Dim- to the output V- or V+, otherwise the driver will not work properly.
- 2. The dimmer can also be replaced by an active 0-10V voltage source signal or passive components like zener.
- 3. When dimming voltage X point is set to be smaller than Y point, the dimming curve is positive logic, conversely, when X point is set to be bigger than Y point, the dimming curve is negative logic.
- 4. For best dimming accuracy, the difference between X point and Y point is advised more than 4V.
- 5. Dimming off voltage adjustable.

Time Dimming

Time dimming control includes 3 kinds of modes, they are Self Adapting-Midnight, Self Adapting-Percentage and Traditional Timer.

- Self Adapting-Midnight: Automatically adjusts the dimming curve based on the on-time of past two days (if difference <15 minutes), assuming that the center point of the dimming curve is midnight local time
- **Self Adapting-Percentage**: Automatically adjusts the on-time of each step by a constant percentage = (actual on-time for the past 2 days if difference <15 min) / (programmed on-time from the dimming curve).
- Traditional Timer: Follows the programmed timing curve after power on with no changes.

Output Lumen Compensation

Output Lumen Compensation (OLC) may be used to maintain constant light output over the life of the LEDs by driving them at a reduced current when new, then gradually increasing the drive current over time to counteract LED lumen degradation.

• Minimum Dimming Level with 5% or 10% Selectable

The minimum dimming level can be set as 5% or 10% by Inventronics Multi Programmer, 10% is default.

Hold Time Adjustable

When AC power is first applied to the LED driver, enabling a "Hold" period can allow devices powered by the Auxiliary voltage to stabilize before the driver fades up to the maximum dimming level. During this period, the driver will not respond to external dimming commands but will respond again after the hold time ends. Both the initial dimming percentage and the duration of this hold period can be adjusted by the Inventronics Multi Programmer. This function is disabled by default

Fade Time Adjustable

There is a "Fade" period after the "Hold" period. The soft-start time and dimming slope applied to all dimming transitions can be adjusted individually. It is adjusted by the Inventronics Multi Programmer. This function is disabled by default.

End Of Life

End-of-Life (EOL) is providing a visual notification to a user that the LED module has reached the end of manufacturer-specified life and that the replacement is recommended. Once active, an indication is given at each power-up of the driver, which the driver indicates this through a lower light output during the first 1 minute before normal operation is continued.

Digital Dimming

Inventronics Digital Dimming is a UART (Universal Asynchronous Receive Transmitter) based communication protocol. Please refer to **Inventronics Digital Dimming** file for details.

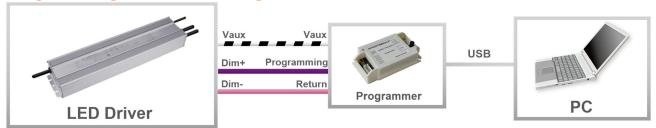
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Programming Connection Diagram



Note: The driver does not need to be powered on during the programming process.

Please refer to <u>PRG-MUL2</u> (Programmer) datasheet for details.

Mechanical Outline

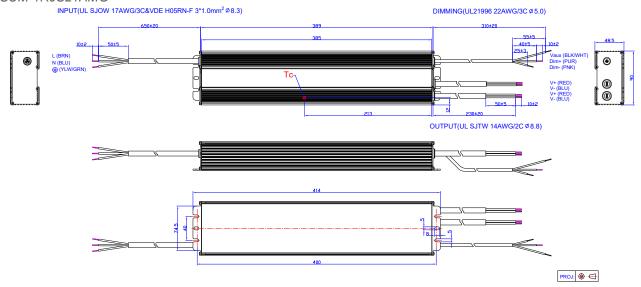
Unspecified tolerance:±1

SUM-1K0SxxxMx

Rev.C

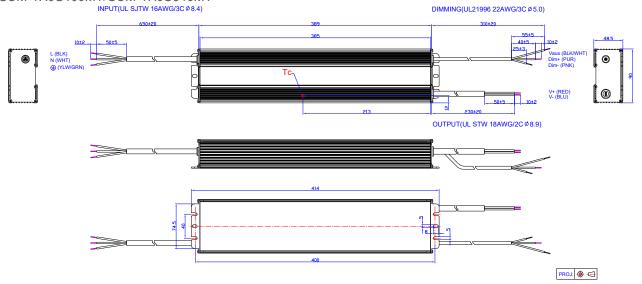
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SUM-1K0S21AMG



Unspecified tolerance:±1

SUM-1K0S400MT/SUM-1K0S840MT



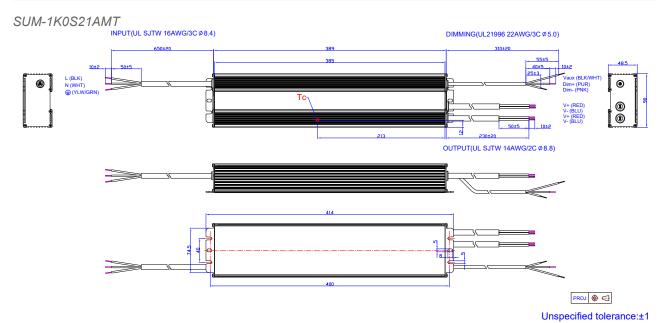
Unspecified tolerance:±1

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RoHS Compliance

Our products comply with reference to RoHS Directive (EU) 2015/863 amending 2011/65/EU, calling for the elimination of lead and other hazardous substances from electronic products.

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1000W Programmable Driver with INV Digital Dimming

Revision History

| Change Date | Rev. | Description of Change | | |
|----------------|------|---------------------------|------|---------|
| | | Item | From | То |
| 2022-08-15 | А | Datasheet Release | / | / |
| 2023-04-04 | В | Product Photograph | / | Updated |
| | | SUM-1K0S400Mx | / | Added |
| | | Efficiency vs. Load | / | Updated |
| | | Power Factor | / | Updated |
| | | Total Harmonic Distortion | / | Updated |
| | | Protection Functions | / | Updated |
| | | Mechanical Outline | / | Updated |
| 2024-01-02 | С | Format | / | Updated |
| | | Features | / | Updated |
| | | Inrush Current Waveform | / | Updated |
| | | Dimming | / | Updated |

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